

In single-var, derivatives and integrals are essentially opposites

$$\frac{df}{dx} = g$$

$$\text{FTC} : \int_a^b g(x) dx = f(b) - f(a)$$

So far we have the following in multivar

① Differentiation \rightarrow partial differentiation

Given $f(x, y)$ (two inputs, one output)

have $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$ or together:

$$\text{gradient } \nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) \quad (\text{two outputs? inputs})$$

Q Given ∇f (and maybe some initial cond $f(x_0, y_0) = z_0$) can we integrate?

We learned about a kind of integration in multivariable: takes a function $g(x, y)$ with 2 inputs and one output and a region R .

Then

$$\iint_R g(x, y) dx dy \text{ is a number} \quad (\text{one output})$$

Want something like FTC:

i.e., given $\vec{a} \in \mathbb{R}^2$ and $\vec{b} \in \mathbb{R}^2$

$$\text{want } f(\vec{b}) - f(\vec{a}) = \int_{\vec{a}}^{\vec{b}} \nabla f d?$$

if we write the RHS in terms of the double integration we learned, get 2 problems:

① ∇f has 2 outputs, not 1

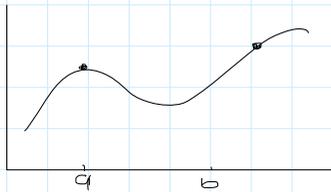
② How to choose R in terms of \vec{a} and \vec{b} ?

Need a new kind of integration s.t.

$$f(\vec{b}) - f(\vec{a}) = \int_{\vec{a}}^{\vec{b}} \nabla f d(\text{something})$$

this will be line integration [Co] 138

Recall what happens in 1D



Q/ How to find $F(b) - F(a)$ in terms of $F'(x)$?

A/ We divide $[a, b]$ into little pieces I_1, \dots, I_N eg $I_1 = [a, a + \frac{(b-a)}{N}]$

$$x_i = a + \frac{i(b-a)}{N} \text{ so } I_i = [x_{i-1}, x_i]$$

$$\Delta x_i = \text{length}(I_i) = \frac{b-a}{N} = x_i - x_{i-1}$$

Q/ What is ΔF over I_i ?

A/ $F(x_i) - F(x_{i-1})$ ← exact

$\Delta x_i \cdot F'(x_i)$ ← approx

↳ gets better as $N \rightarrow \infty$

$$F(b) - F(a) = F(x_N) - F(x_0) = \sum \Delta F$$

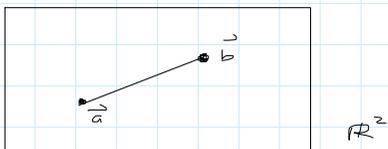
$$= \sum F(x_i) - F(x_{i-1})$$

$$= F(x_1) - F(x_0) + F(x_2) - F(x_1) + \dots + F(x_n) - F(x_{n-1})$$

$$\approx \sum \Delta x_i \cdot F'(x_i)$$

↳ Riemann sum whose $\lim_{N \rightarrow \infty}$ is $\int_a^b F'(x) dx$

Now, in 2D



$$(x_i, y_i) = a + \frac{i(b-a)}{N}$$

Notice

$$(x_0, y_0) = a \quad (x_N, y_N) = b$$

Now

$$F(b) - F(a) = F(x_N, y_N) - F(x_0, y_0)$$

$$= \sum_{i=1}^N F(x_i, y_i) - F(x_{i-1}, y_{i-1})$$

$$= \sum \Delta F$$

$$\sum_{i=1}^N f(x_i, y_i) - f(x_{i-1}, y_{i-1})$$

$$= \sum_{i=1}^N \Delta F \leftarrow (x_{i-1}, y_{i-1}) \rightarrow (x_i, y_i)$$

Q/ How to estimate ΔF using derivatives?

A/

NOTICE we have $\Delta x_i = x_i - x_{i-1}$
 $\Delta y_i = y_i - y_{i-1}$

$$\Delta F \approx \Delta x_i \frac{\partial F}{\partial x}(x_i, y_i) + \Delta y_i \frac{\partial F}{\partial y}(x_i, y_i)$$

$$\text{So } f(\vec{b}) - f(\vec{a}) = \sum_{i=1}^N \Delta F$$

$$\approx \sum_{i=1}^N \left[\Delta x_i \frac{\partial F}{\partial x} + \Delta y_i \frac{\partial F}{\partial y} \right] \text{ will define line integrals using lines like this}$$

$$= \sum_{i=1}^N (\Delta x_i, \Delta y_i) \cdot \underbrace{\left(\frac{\partial F}{\partial x}, \frac{\partial F}{\partial y} \right)}_{\nabla F}$$

$$= \sum_{i=1}^N \nabla F \cdot (\Delta x_i, \Delta y_i)$$

$$= \sum_{i=1}^N \nabla F \cdot \Delta \vec{r}_i$$

$$\text{We call } \lim_{N \rightarrow \infty} \sum_{i=1}^N \nabla F \cdot \Delta \vec{r}_i = \int_{\vec{a}_1}^{\vec{b}_1} \nabla F \cdot d\vec{r}$$

$$= \int_{\vec{a}_1}^{\vec{b}_1} \nabla F \cdot (dx, dy)$$

$$= \int_{\vec{a}_1}^{\vec{b}_1} \left(\frac{\partial F}{\partial x}, \frac{\partial F}{\partial y} \right) \cdot (dx, dy)$$

$$= \int_{\vec{a}_1}^{\vec{b}_1} \frac{\partial F}{\partial x} dx + \frac{\partial F}{\partial y} dy$$

In general, for a fcn w/ 2 outputs & inputs (like ∇F)
 we can define

$$(P(x, y), Q(x, y)) = (P, Q)$$

$$\text{we can define } \int_{\vec{a}_1}^{\vec{b}_1} (P, Q) \cdot d\vec{r} = \int_{\vec{a}_1}^{\vec{b}_1} P dx + Q dy$$

$$= \lim_{N \rightarrow \infty} \sum_{i=1}^N P(x_i, y_i) \cdot \Delta x_i + Q(x_i, y_i) \cdot \Delta y_i$$

When we defined $\int_{\vec{a}}^{\vec{b}} (P, Q) \cdot (dx, dy)$, we set

$$(x_i, y_i) = \vec{a} + i \frac{(\vec{b} - \vec{a})}{N}$$

Such a point is on the line segment from \vec{a} to \vec{b} .

More generally, we can integrate $(P, Q) \cdot (dx, dy)$ along any curve from \vec{a} to \vec{b} .

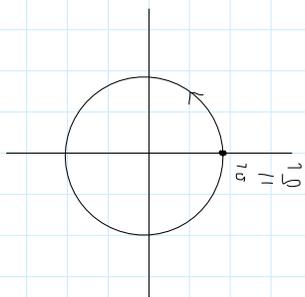
\hookrightarrow 1D subset of \mathbb{R}^2 that has a connected start and endpoint

If $\vec{a} = \vec{b}$, we call a curve from \vec{a} to \vec{b} a loop
 \rightarrow trivial loop stays at \vec{a}

Often, we parameterize a path, using t in some interval in \mathbb{R}^1

eg, $\vec{a} = \vec{b} = (1, 0)$ in \mathbb{R}^2

consider the loop given by the unit circle (counterclockwise)



Q/ How to parameterize?
 (You can parameterize same path in diff ways.)

eg

$$(x(t), y(t)) = (\cos(t), \sin(t))$$

$$t \in [0, 2\pi]$$

$$(x(t), y(t)) = (\cos(2\pi t), \sin(2\pi t))$$

$$t \in [0, 1]$$

$$(x, y) = (\cos(2\pi t^2), \sin(2\pi t^2))$$

$$t \in [0, 1]$$

A/ Given a path C from \vec{a} to \vec{b} , will define

$$\int_C (P, Q) \cdot (dx, dy)$$

To calculate it, we need to choose a parameterization of C , but the value of the integral is ind to the parameterization

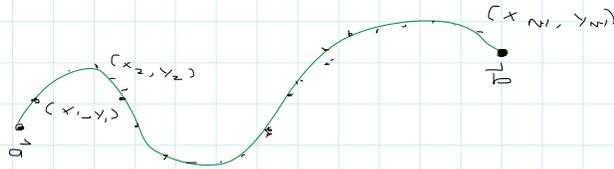
Abstract definition of $\int_C P dx + Q dy$

For each N , choose a partition of C into smaller paths.

Suppose C is from \vec{a} to \vec{b} .

$$\begin{aligned} \hookrightarrow \text{Set } (x_0, y_0) &= \vec{a} \\ (x_N, y_N) &= \vec{b} \end{aligned}$$

\hookrightarrow Choose $(x_1, y_1), (x_2, y_2), \dots$, generally (x_i, y_i) on path C .



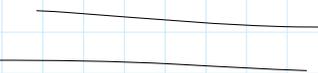
form Riemann sum:

$$\sum_{i=1}^N P(x_i, y_i) \cdot \Delta x_i + Q(x_i, y_i) \cdot \Delta y_i$$

$$\Delta x_i = x_i - x_{i-1}$$

$$\Delta y_i = y_i - y_{i-1}$$

want as $N \rightarrow \infty$, the $\max(\Delta x_i)$ and Δy_i go to 0



equivalently: mesh = $\max \Delta x_i, \Delta y_i$

$$\begin{aligned} \int_C P dx + Q dy &= \lim_{N \rightarrow \infty} \sum_{i=1}^N P(x_i, y_i) \Delta x_i + Q(x_i, y_i) \Delta y_i \\ &= \lim_{\text{mesh} \rightarrow 0} \sum \end{aligned}$$

$$\begin{aligned} \int_C P dx + Q dy &= \int_C P \frac{dx}{dt} + Q \frac{dy}{dt} \\ &= \int_{t=a}^{t=b} \left(P \frac{dx}{dt} + Q \frac{dy}{dt} \right) dt \end{aligned}$$